

Real-time Global Flood Monitoring and Forecasting using an Enhanced Land Surface Model with Satellite and NWP model based Precipitation

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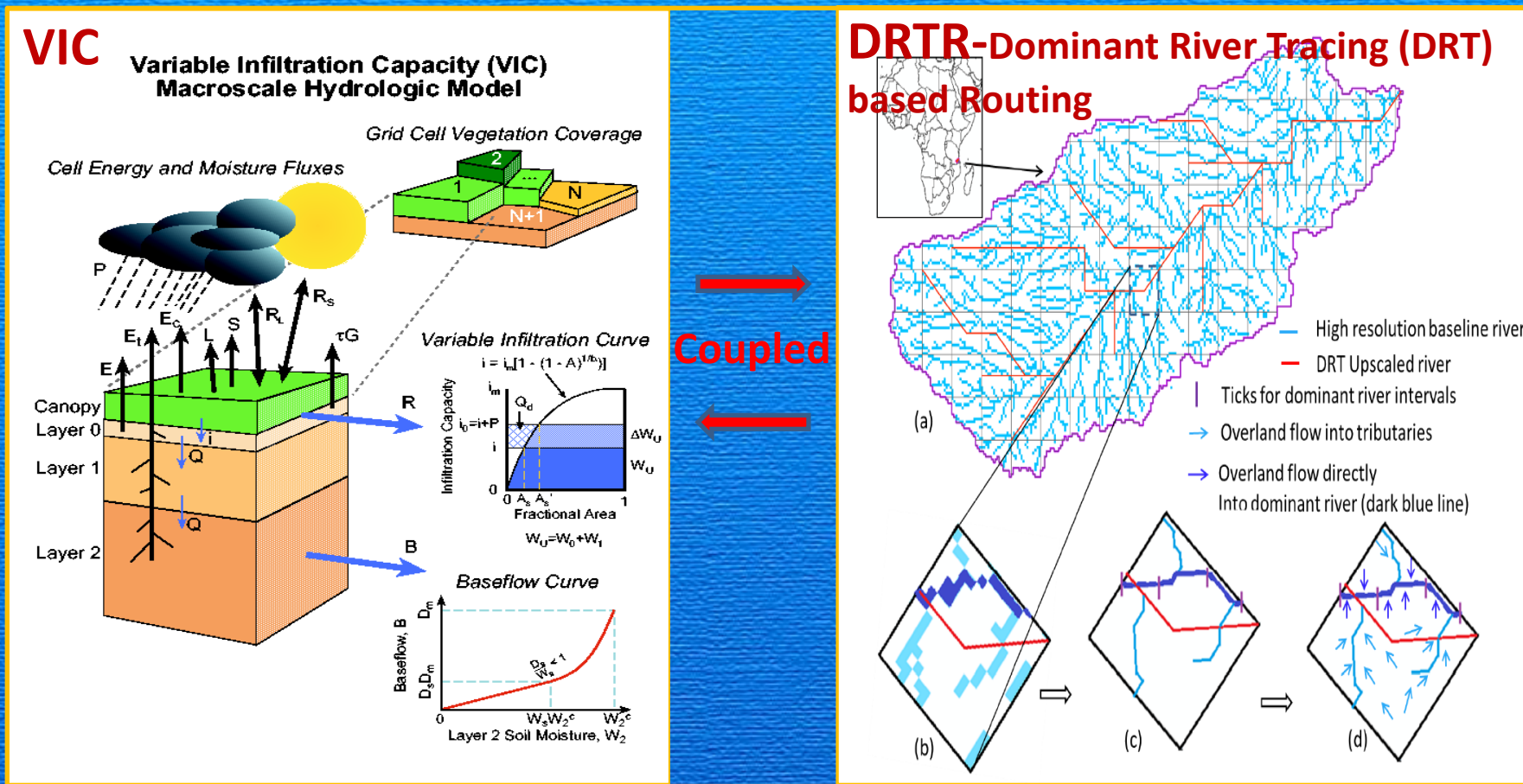


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Dominant river tracing-Routing Integrated with VIC Environment (DRIVE) model

(Wu et al., 2011, 2012, 2013 *Water Resources Research*)



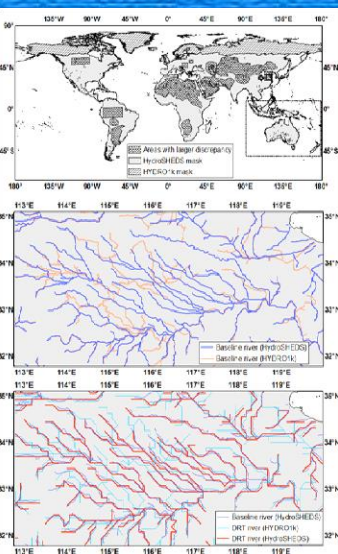
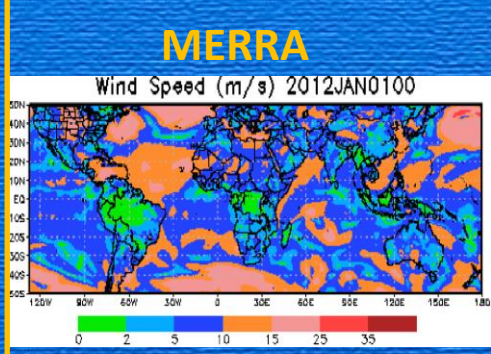
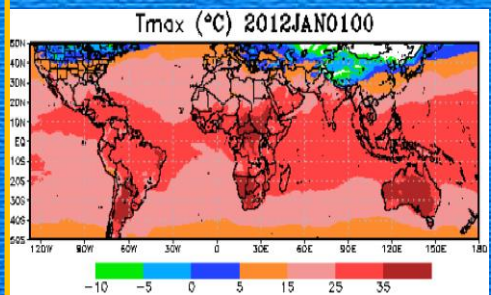
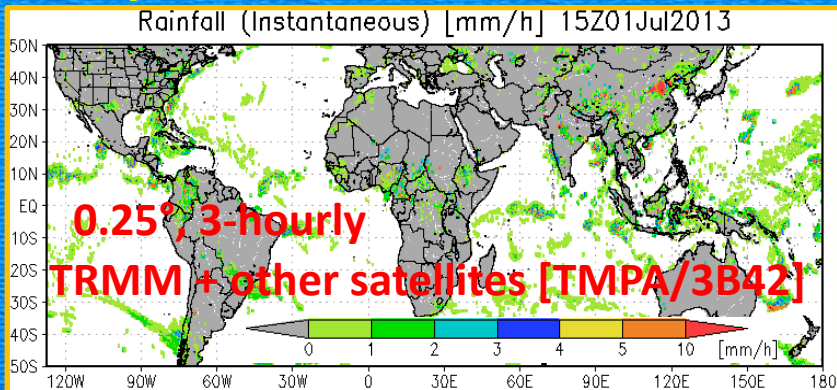
University of Washington

University of Maryland

Global Flood Monitoring System (GFMS) is running quasi-globally (50°S-50°N) every three hours at 1/8th degree, and routing is also running at 1km resolution.

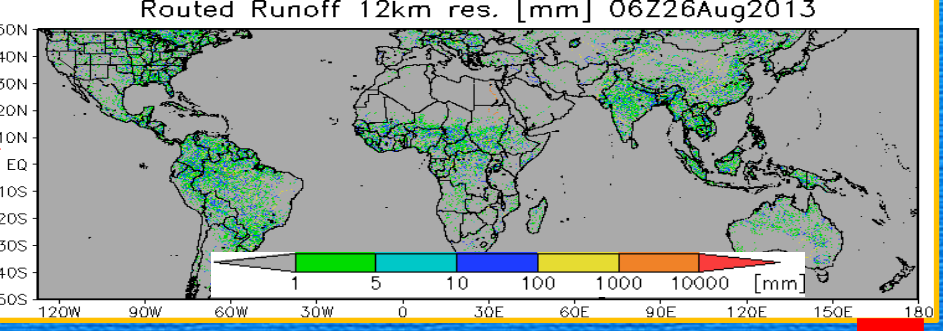
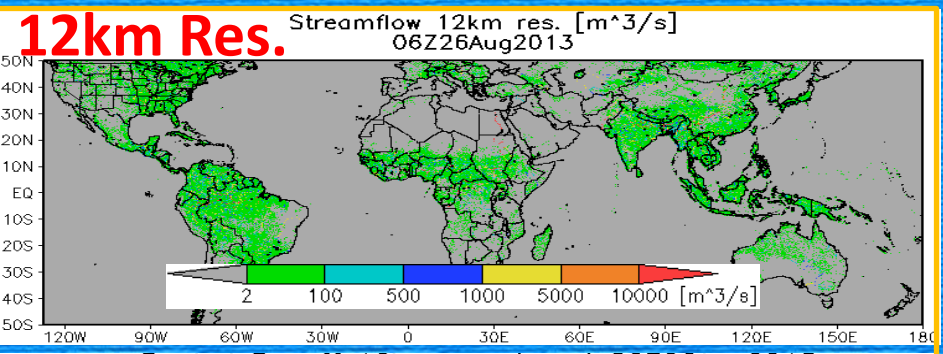
Global Flood Monitoring System (GFMS)/DRIVE model

<http://flood.umd.edu>

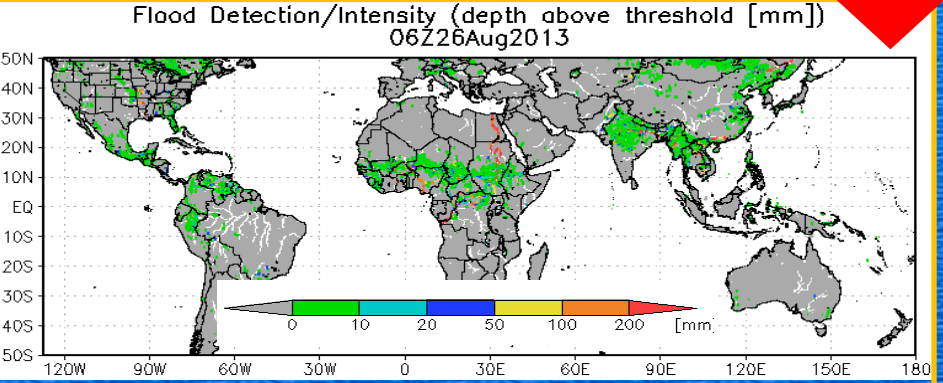


DRT, Wu et al., 2011,2012

Soil, Vegetation, Snowbands (Princeton)
DEM (1km, HydroSHEDS)



15yr Retrospective simulation



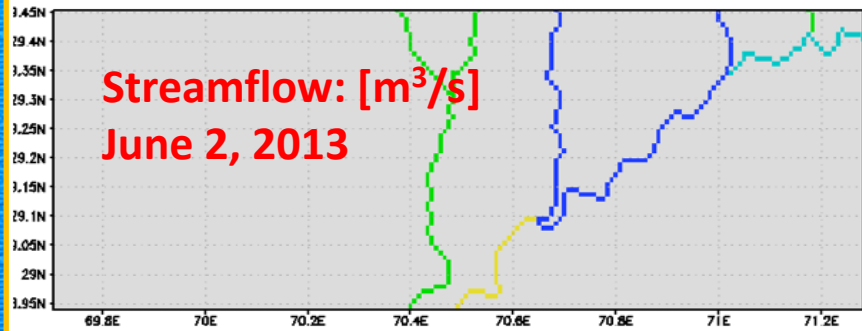
Flooding at a point, if:

$R > P_{95} + \delta$ and $Q > 10 \text{ m}^3/\text{s}$

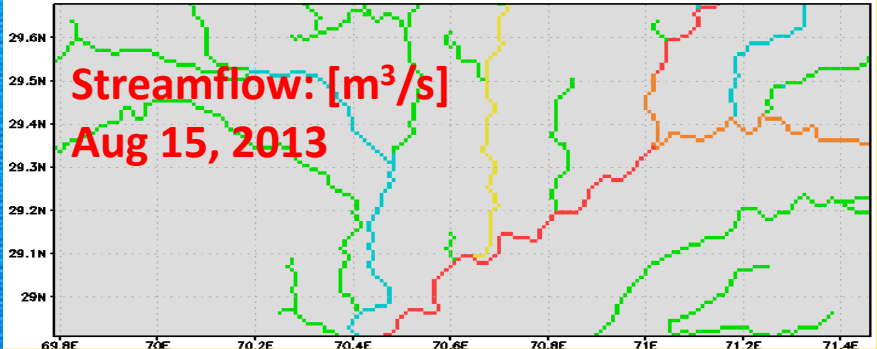
R: routed runoff (mm);
 P₉₅: 95th percentile value of routed runoff;
 δ: temporal standard deviation of routed runoff;
 Q: discharge (m³/s)

1 km Res.

Streamflow 1km res. [m^3/s]
09Z02Jun2013

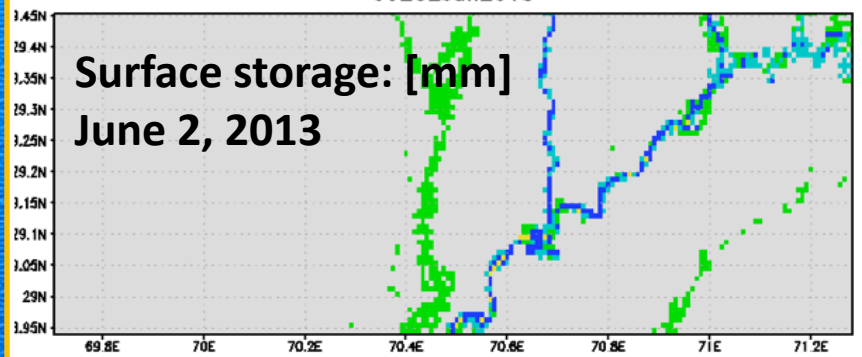


Streamflow 1km res. [m^3/s]
12Z15Aug2013

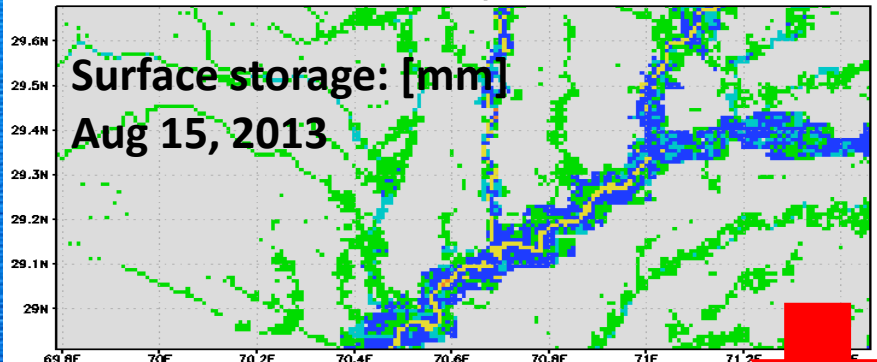


DRIVE/Inundation module

Surface Storage 1km res. [mm]
09Z02Jun2013



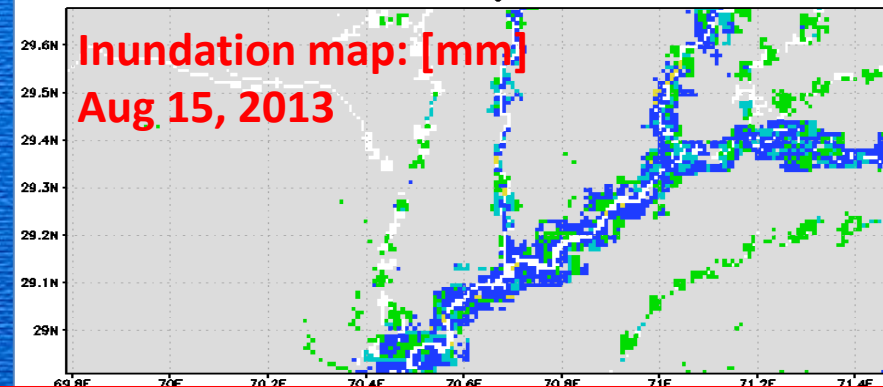
Surface Storage 1km res. [mm]
12Z15Aug2013



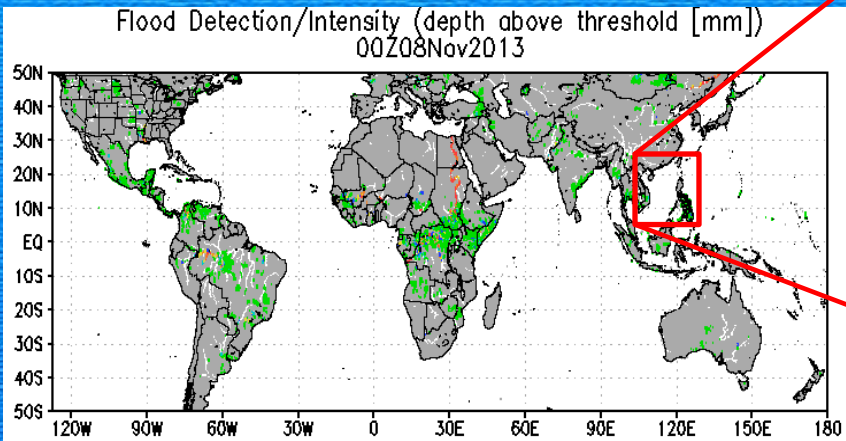
Experimental Inundation Mapping:

- (1) Define a referential water coverage based on retrospective model simulation;
- (2) Apply a small threshold to consider a certain water capacity of each pixel.

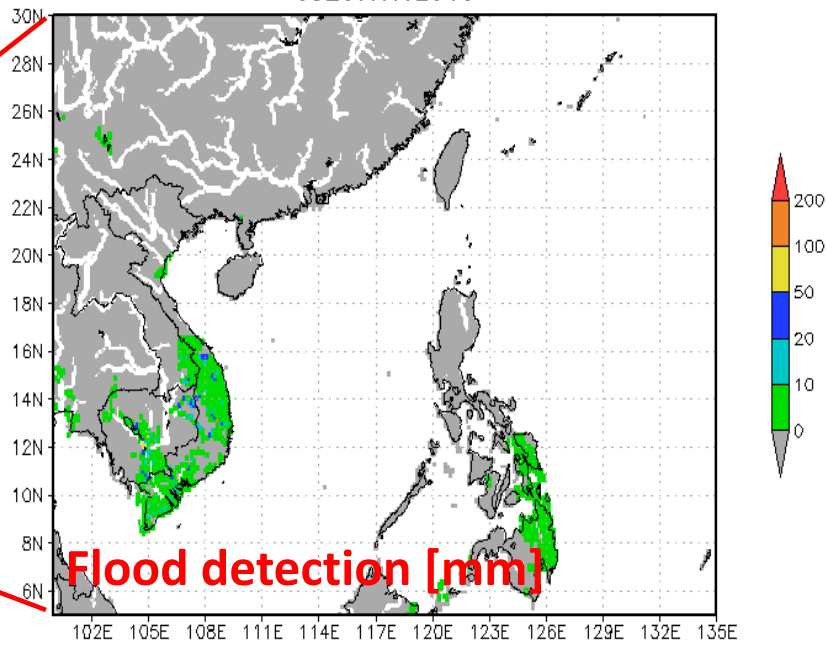
Inundation map 1km res. [mm]
12Z15Aug2013



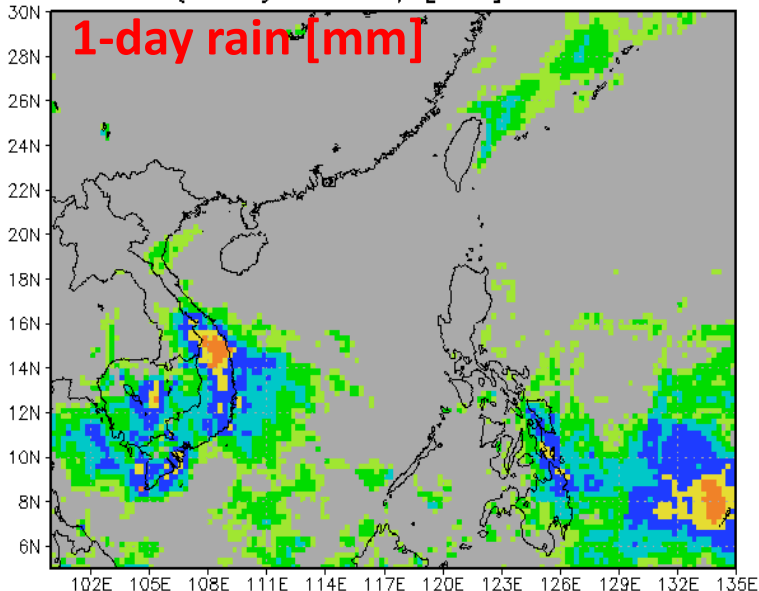
Example of Global to Regional Flood Detection: Recent Flooding caused by "Haiyan" Typhoon (Nov, 2013)



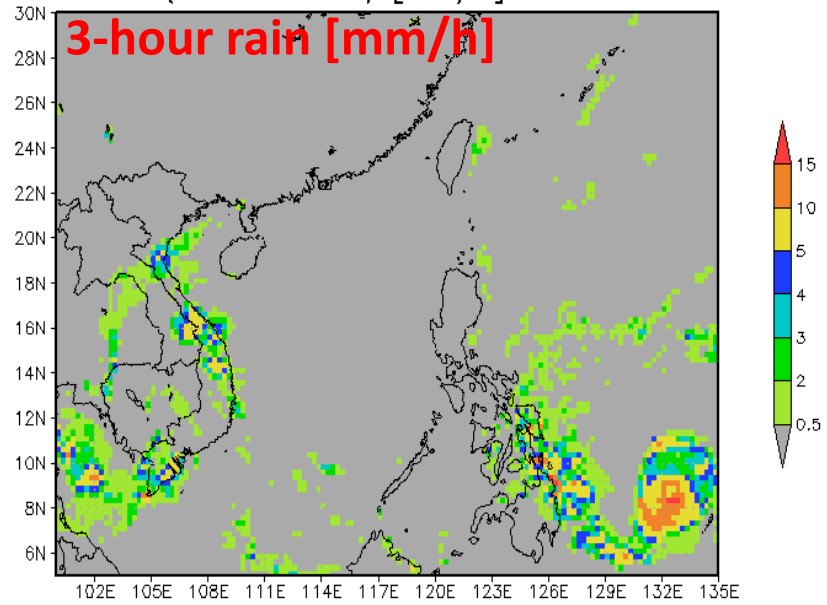
Flood Detection/Intensity (depth above threshold [mm])
03Z07Nov2013



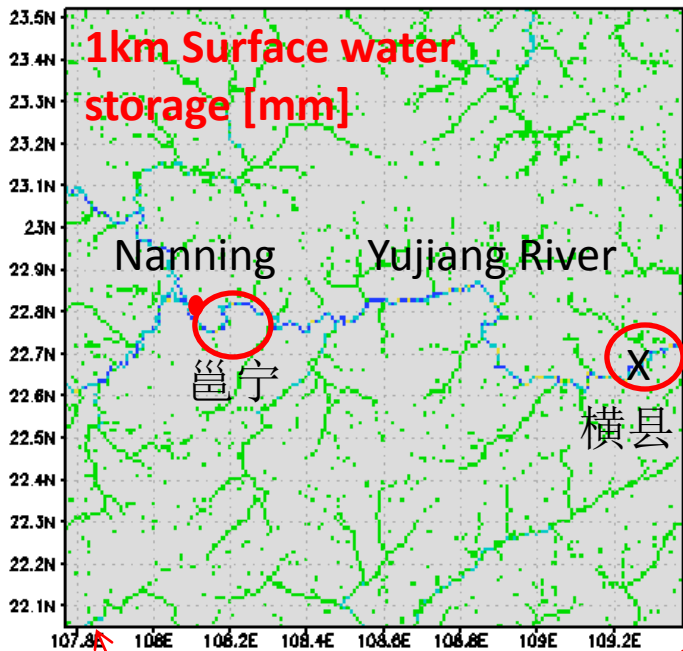
Rainfall (1-day accum.) [mm] 03Z07Nov2013



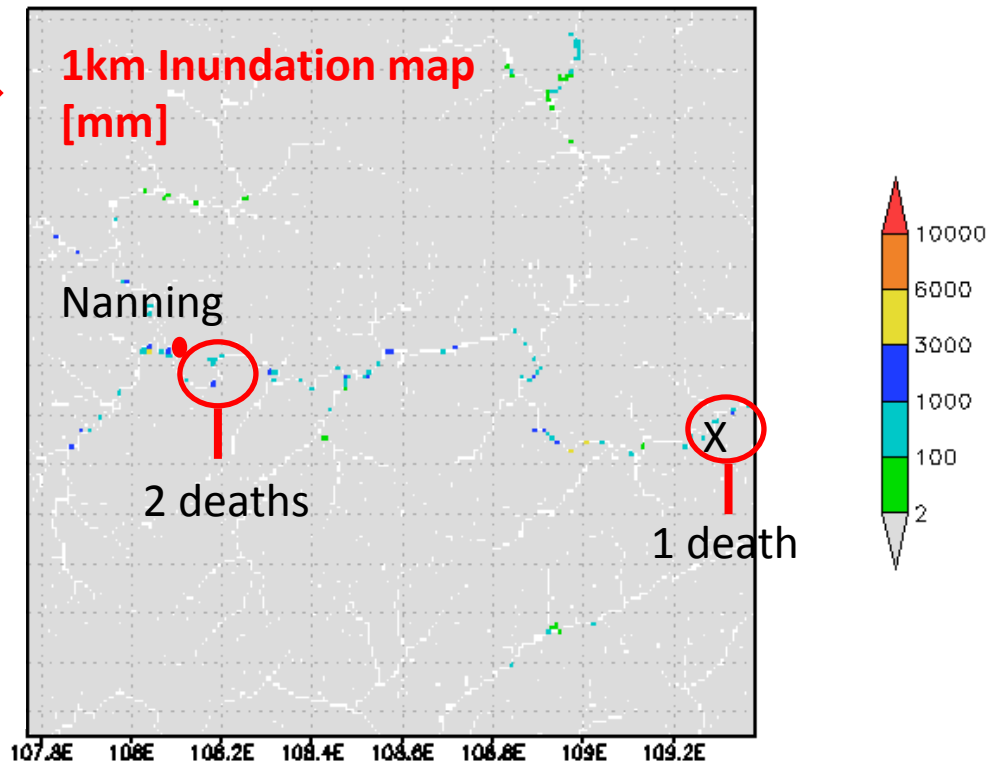
Rainfall (Instantaneous) [mm/h] 00Z07Nov2013



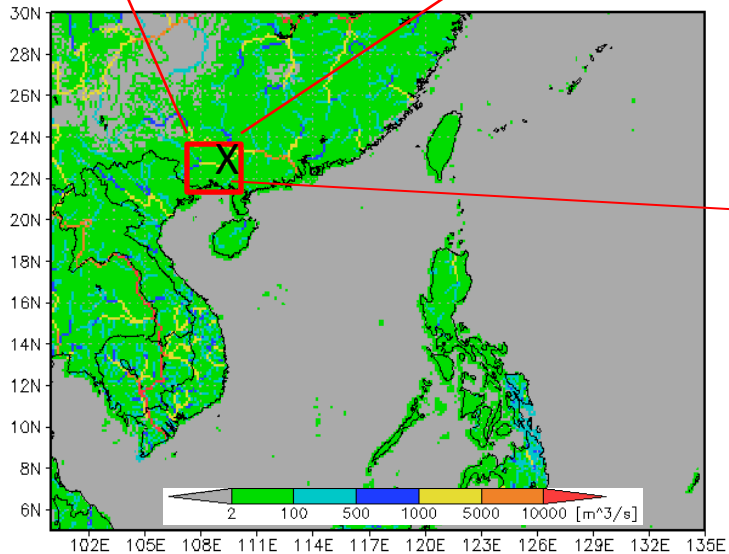
Surface Storage 1km res. [mm]
21Z09Nov2013



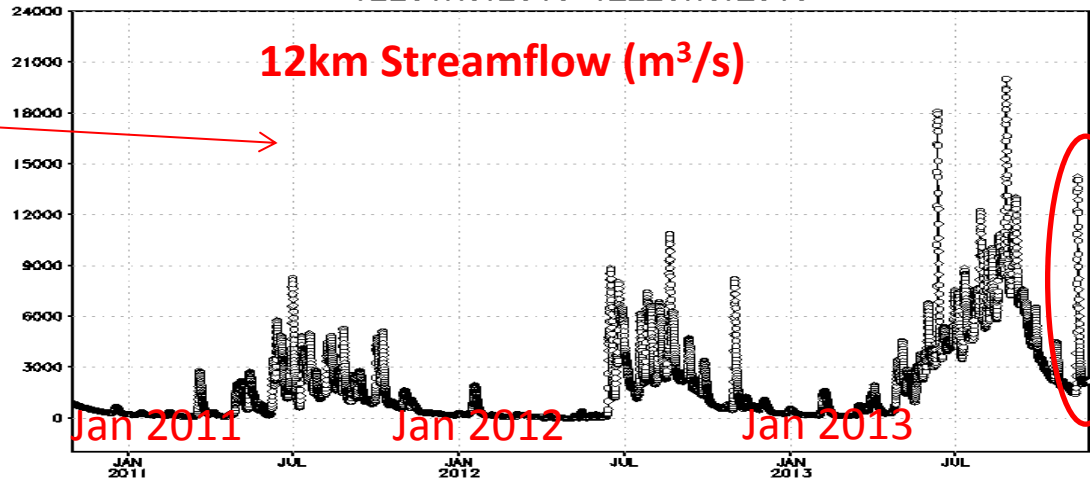
Inundation map 1km res. [mm]
21Z09Nov2013



Streamflow 12km res. [m³/s]
03Z07Nov2013



Streamflow 12km res. [m³/s]
12Z01Nov2010 12Z25Nov2013

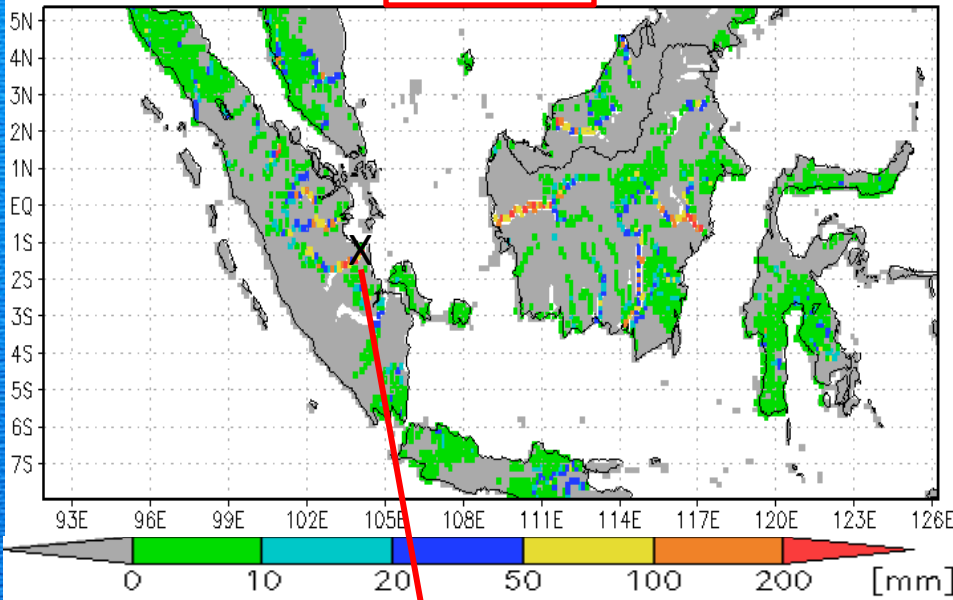


Western Indonesia Flooding

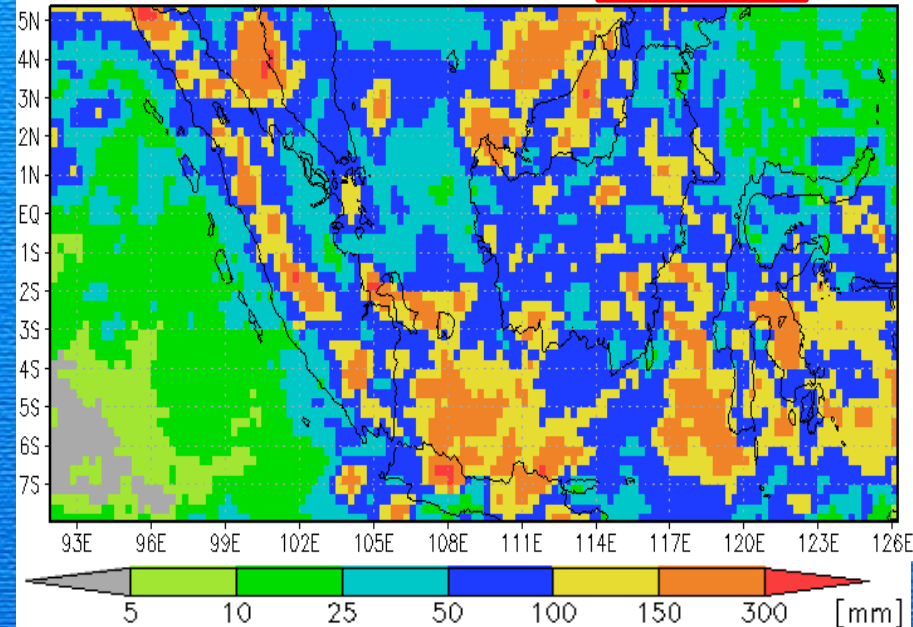
Short term precipitation and flood forecast on Jan 2, 2014

Flood Detection/Intensity (depth above threshold [mm])

21Z06Jan2014

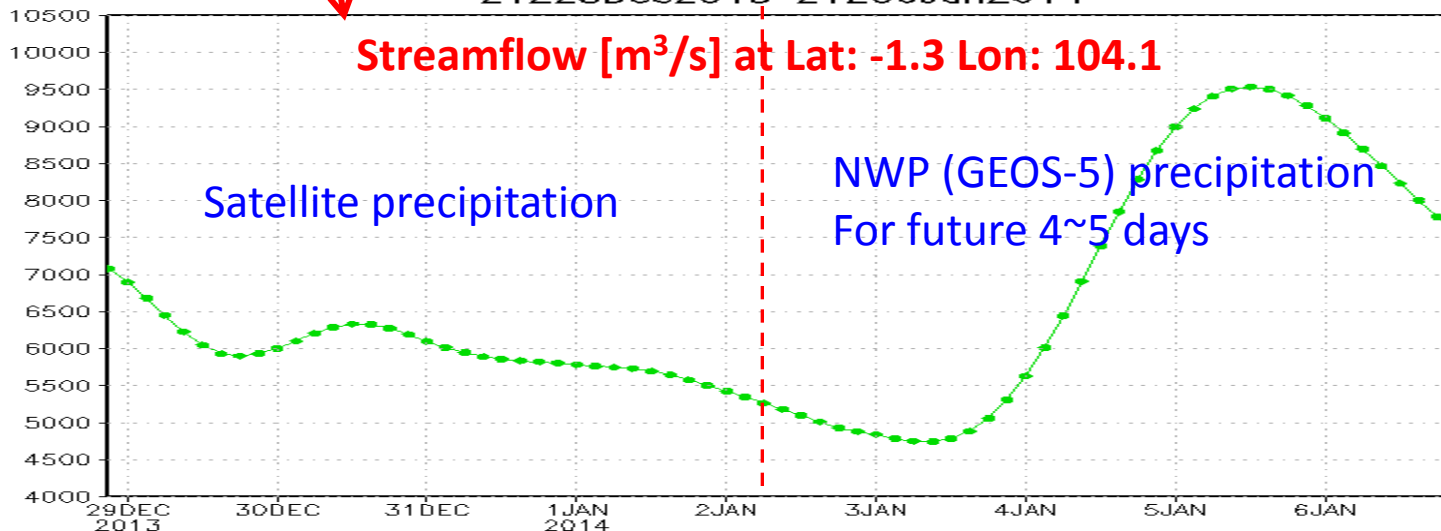


Rainfall (7-day accum.) [mm] 21Z06Jan2014



Streamflow 12km res. [m^3/s]
21Z28Dec2013 21Z06Jan2014

Streamflow [m^3/s] at Lat: -1.3 Lon: 104.1



Global evaluation TMPA real-time (**DRIVE-RT**) and research (rain gauge adjusted, **DRIVE-V7**) [15yrs (1998~), 3-hrly, 1/8° res.]

(1) **Flood event** based evaluation using 2,086 archived flood events by Dartmouth Flood Observatory

(2) **Streamflow** based evaluation at 1,121 river gauges by GRDC, across the globe.

Real-time Global Flood Estimation using Satellite-based Precipitation and a Coupled Land Surface and Routing Model (2013). Wu, Adler et al. Submitted to WRR

[manuscript available on <http://flood.umd.edu/>]

Flood event based evaluation

Flooding at a point

$$R > P_{95} + \delta$$

and

$$Q > 10 \text{ m}^3/\text{s}$$

R : *routed runoff (mm)*

P_{95} : *95th percentile value of routed runoff*

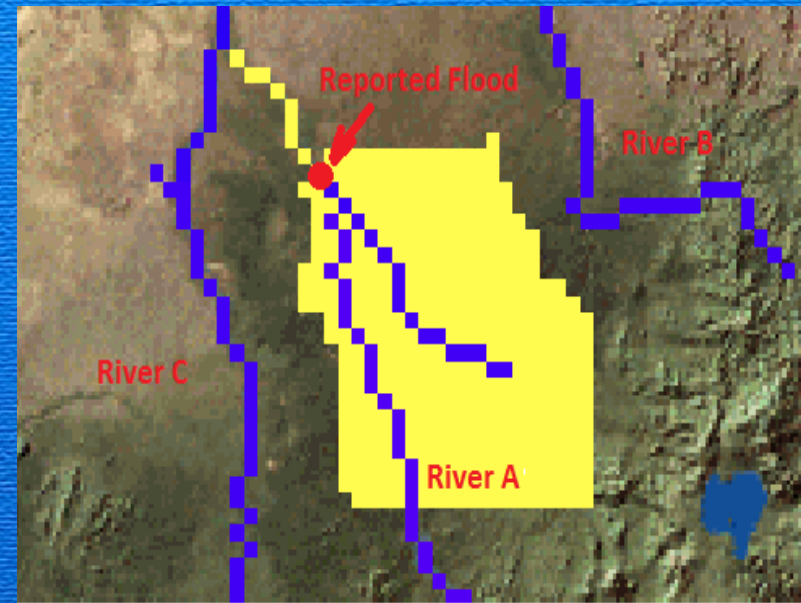
δ : *temporal standard deviation of routed runoff*

Q : *discharge (m^3/s)*

Matching floods between simulated and reported

Temporal window: ± 1 days

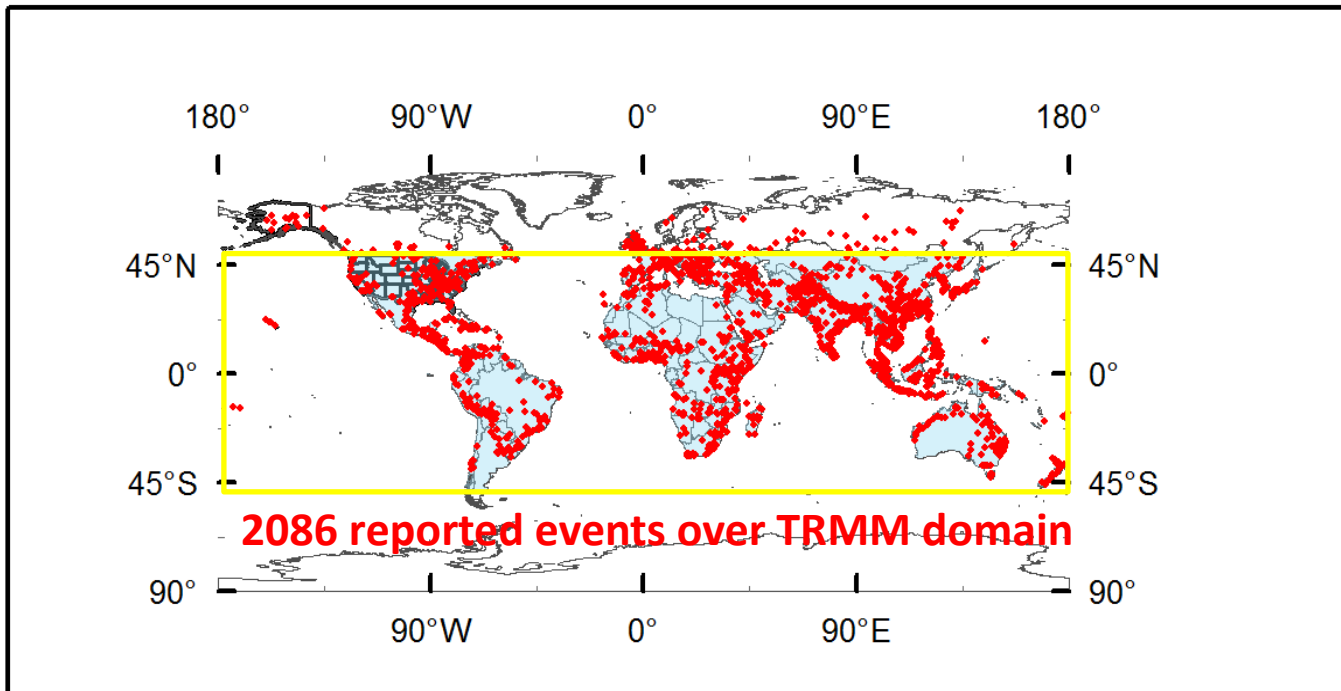
Spatial window: all upstream basin area within ~ 200 km & ~ 100 km downstream stem river



Wu H., R. F. Adler, Y. Hong, Y. Tian, and F. Policelli (2012), *Evaluation of Global Flood Detection Using Satellite-Based Rainfall and a Hydrologic Model*. *J. Hydrometeorol*, 13, 1268.1284.

Flood detection verification against the Dartmouth Flood Observatory (DFO) flood database with 2,086 flood events during 2001-2011, over the TRMM domain

DFO archived flood events (from satellites, news ...)



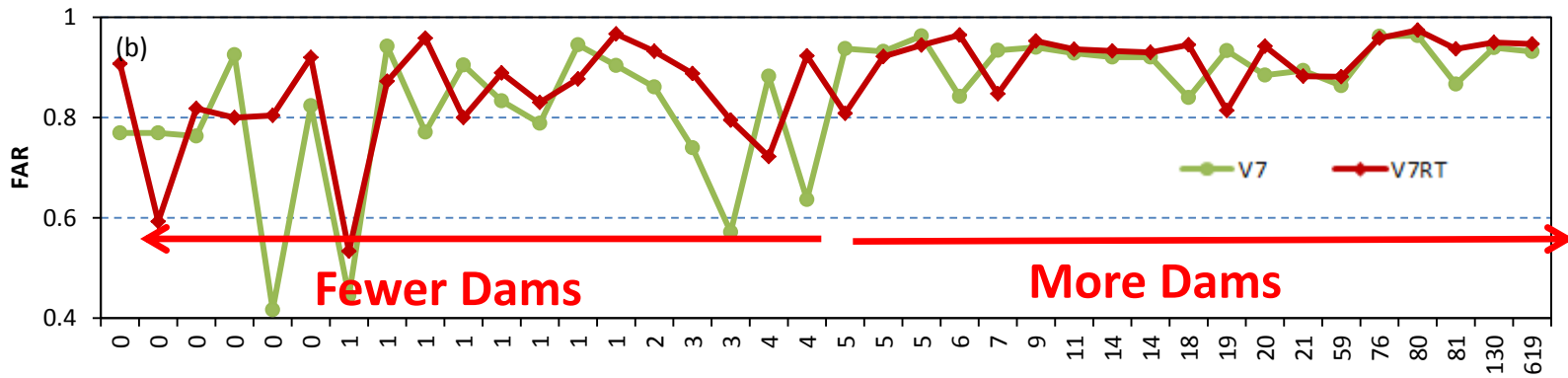
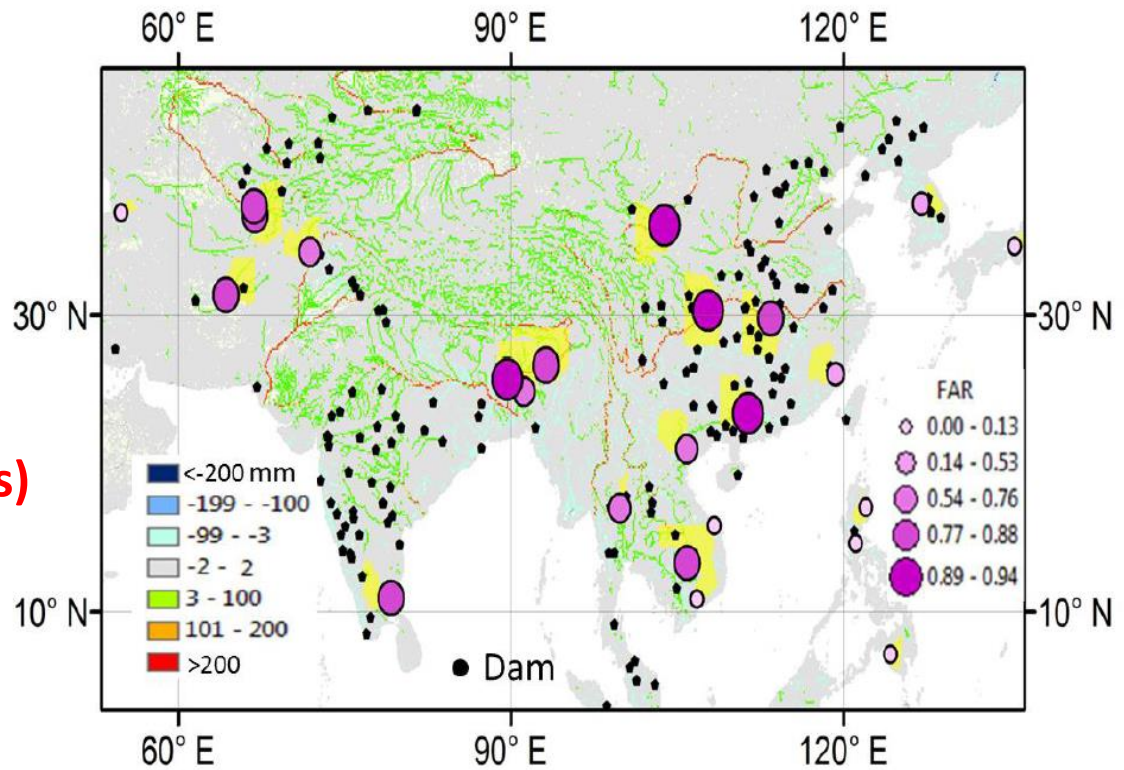
Probability of Detection (POD):

DRIVE-V7: 1,820 (87.2%)

DRIVE-RT: 1,799 (86.2%)

Flood detection

verification against the Dartmouth Flood Observatory (DFO) flood database over the 38 Well Reported Areas (WRAs) for floods with duration more than 3 days.

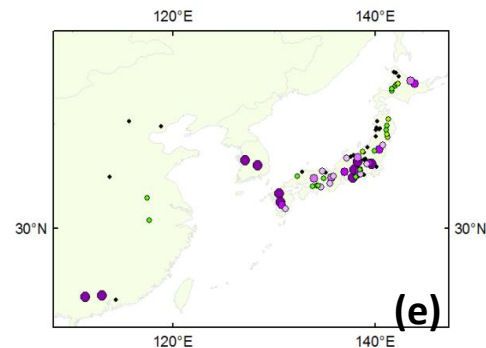
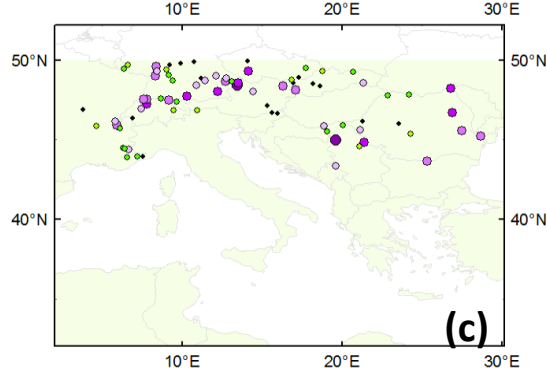
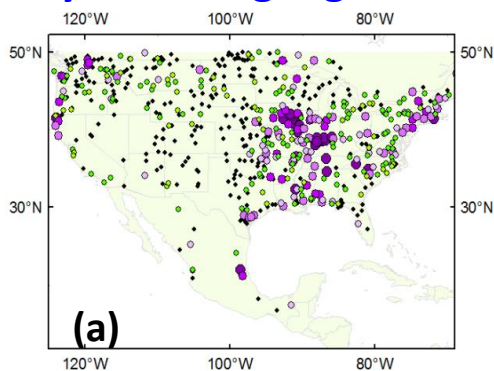


**Bottom line--For 3-day floods in basins with few dams using RT rainfall:
POD ~ 0.9 FAR ~ 0.7**

Comparison with 1,121 GRDC Streamflow Gauges-Nash-Sutcliffe (NSC)

Daily: 32% of gauges with positive values with mean of 0.22

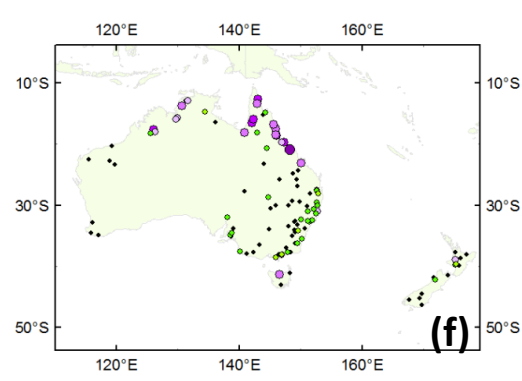
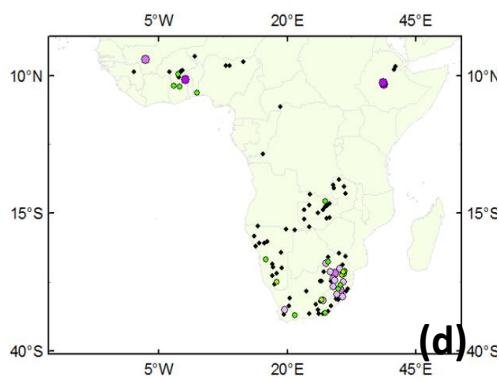
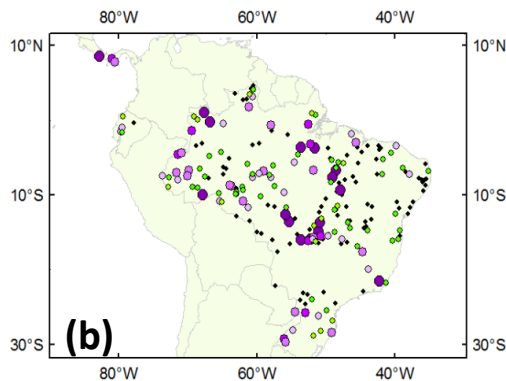
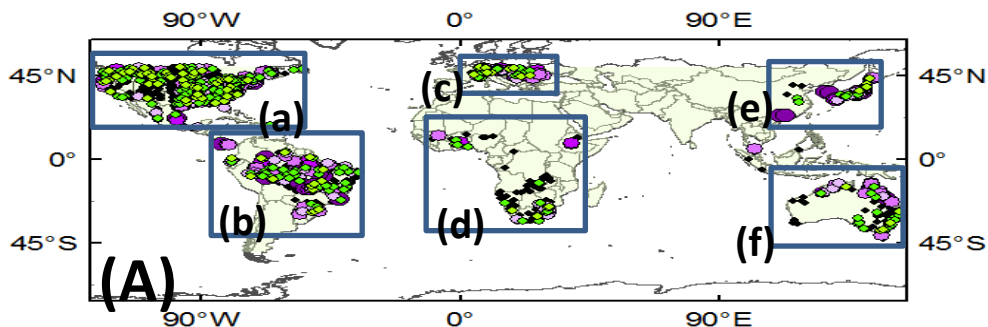
Monthly: 60% of gauges with positive values with mean of 0.39



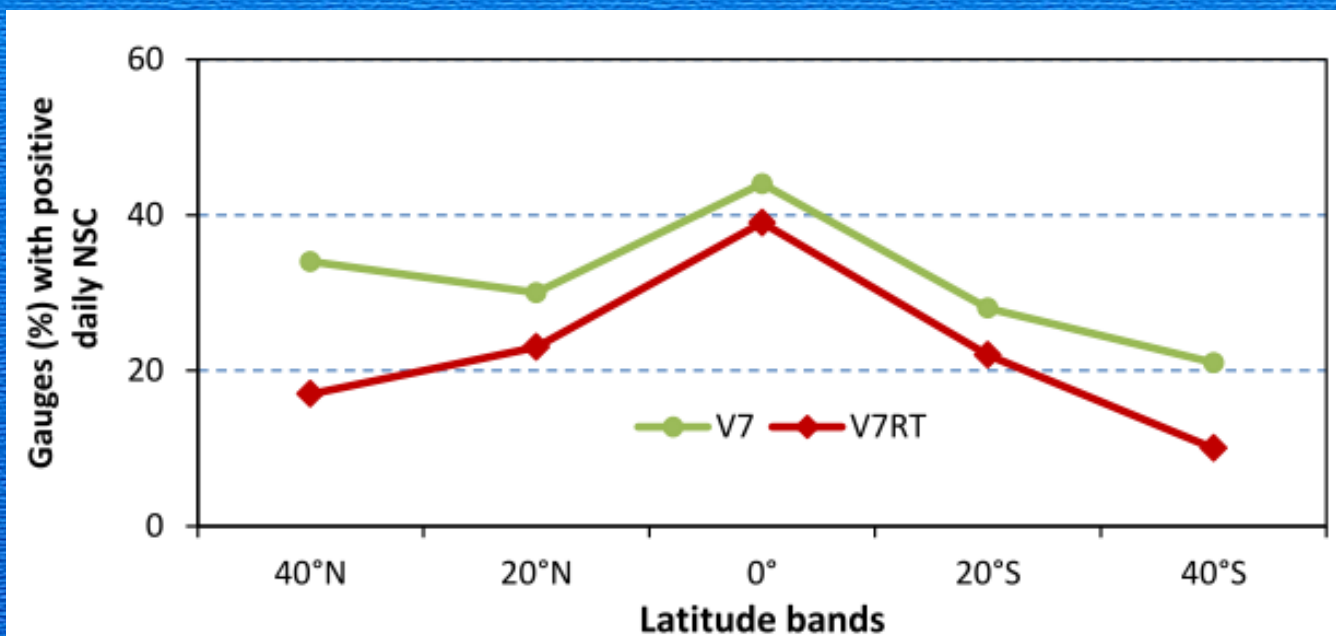
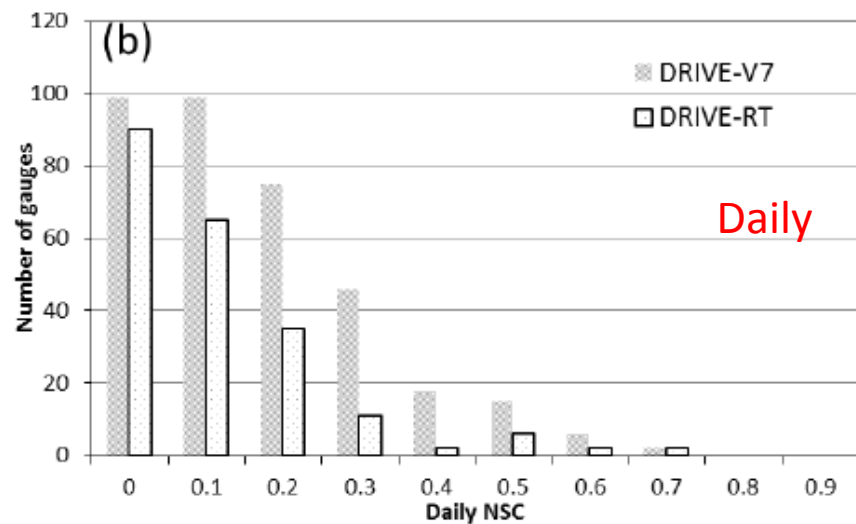
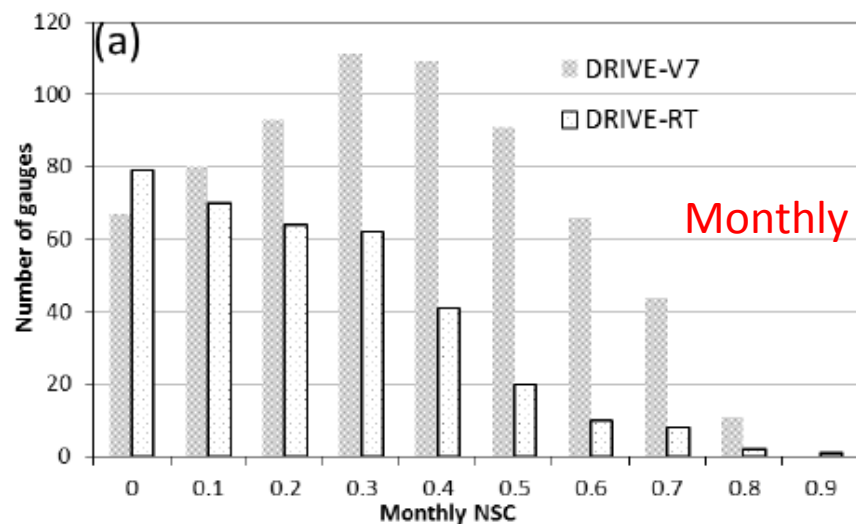
DRIVE-V7 (12km res.)

NSC (monthly)

- 0.00 - 0.15
- 0.16 - 0.40
- 0.41 - 0.50
- 0.51 - 0.60
- 0.61 - 0.70
- 0.71 - 0.90
- GRDC Gauges

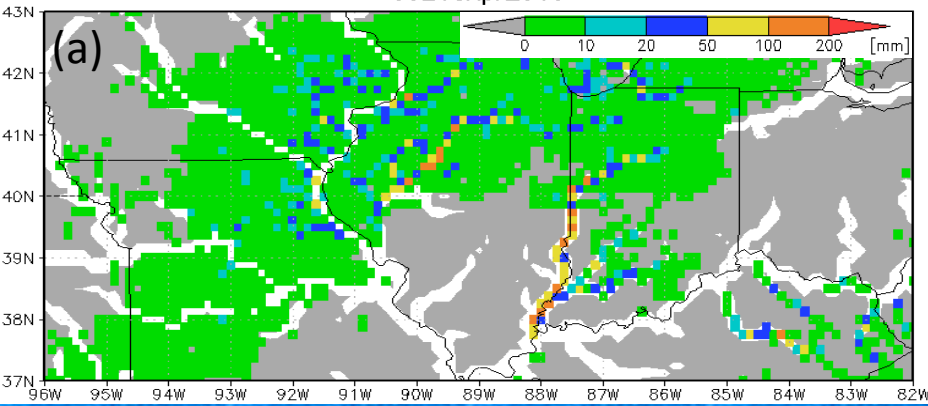


Distribution of the number of gauges with positive monthly and daily NSC metrics for DRIVE-V7 and DRIVE-RT simulation for 2001-2011, respectively

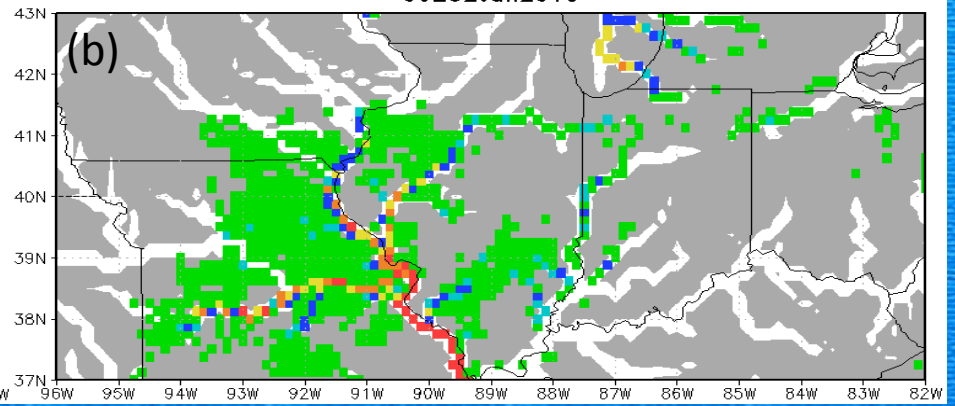


Real-time Evaluation of on-line events

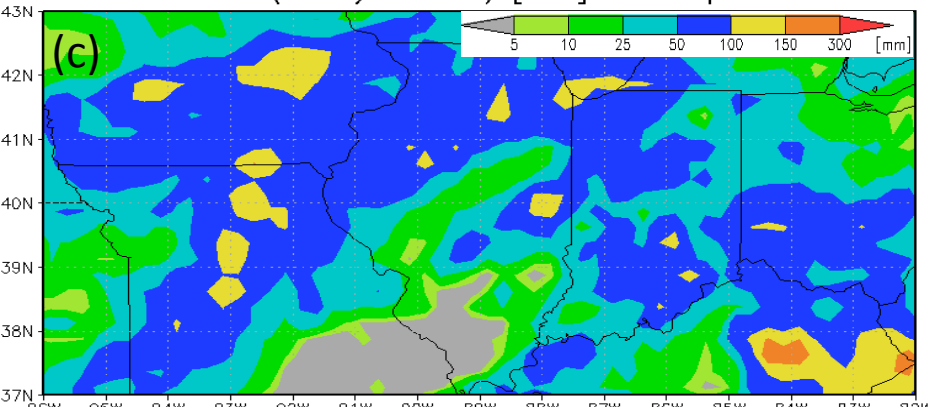
Flood Detection/Intensity (depth above threshold [mm])
09Z18Apr2013



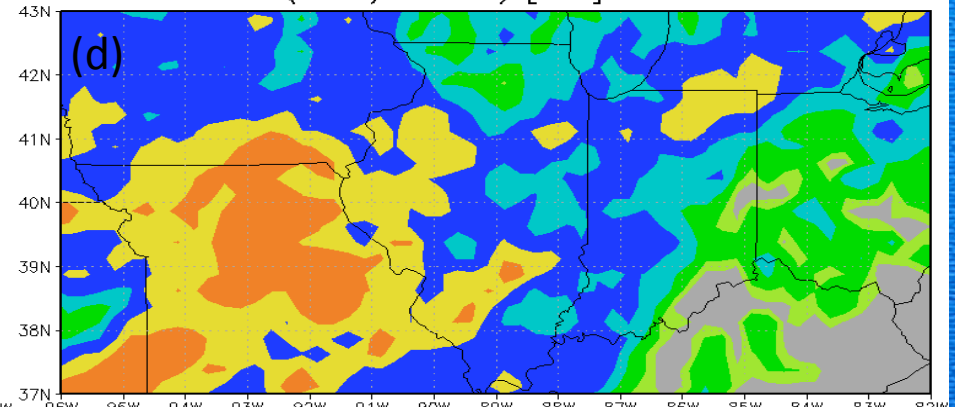
Flood Detection/Intensity (depth above threshold [mm])
09Z02Jun2013



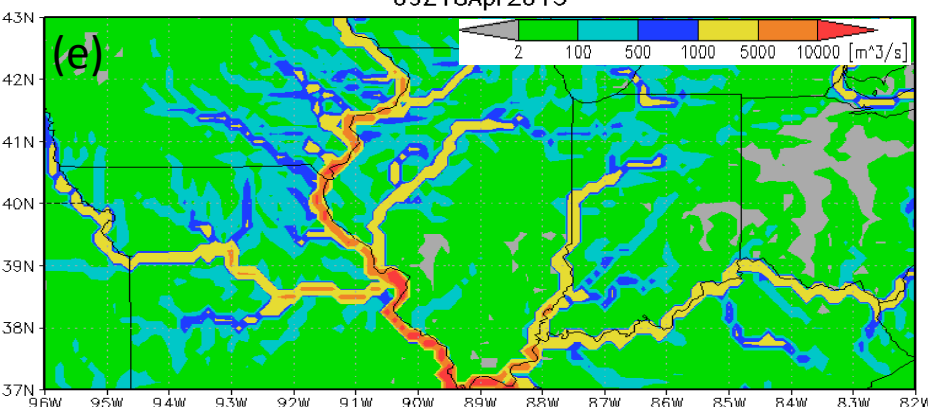
Rainfall (7-day accum.) [mm] 09Z18Apr2013



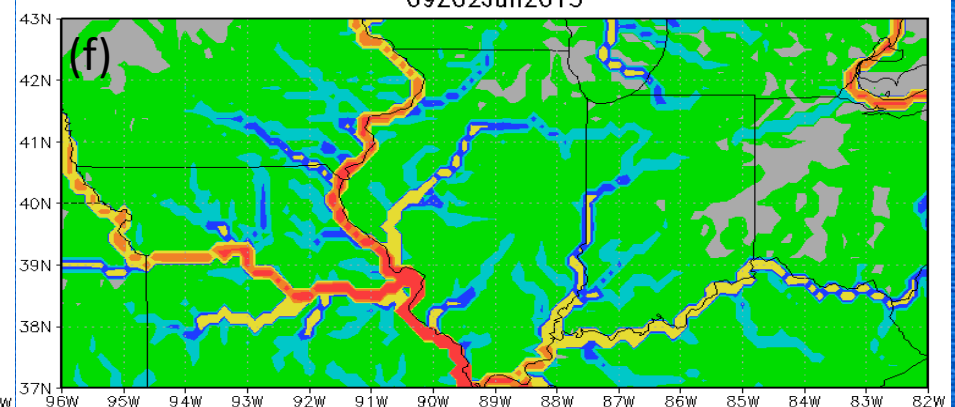
Rainfall (7-day accum.) [mm] 09Z02Jun2013



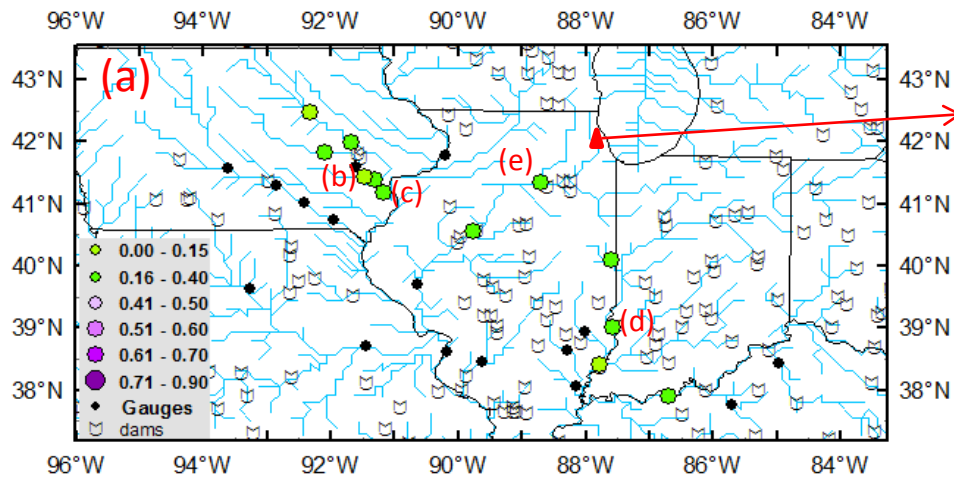
Streamflow 12km res. [m^3/s]
09Z18Apr2013



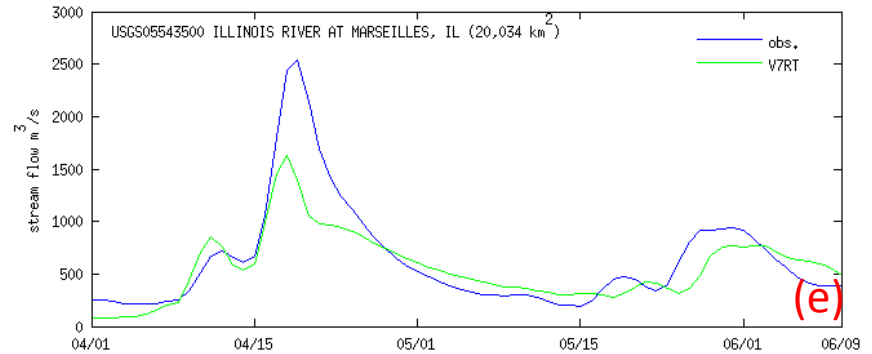
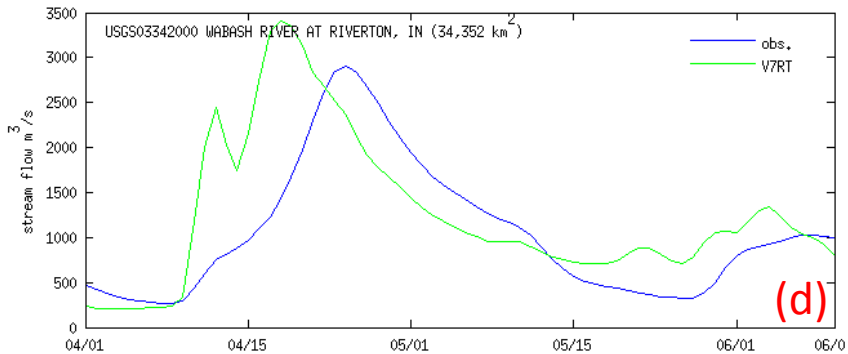
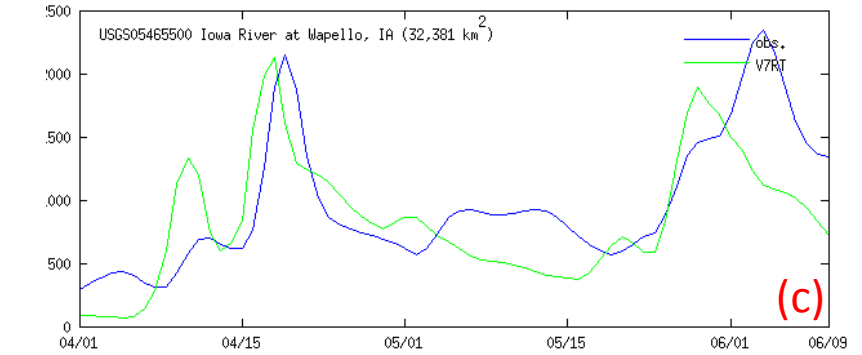
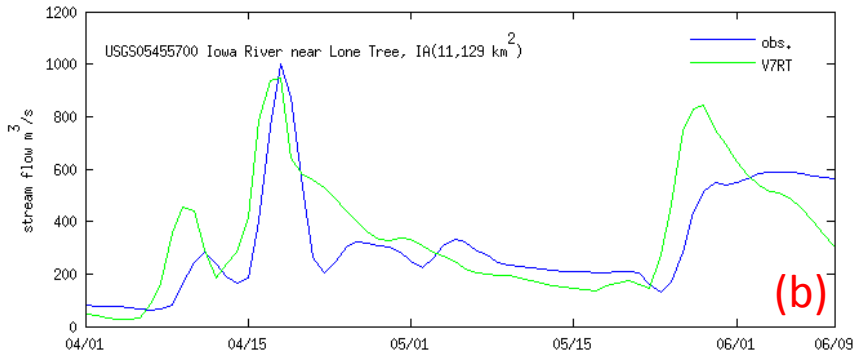
Streamflow 12km res. [m^3/s]
09Z02Jun2013



41% (12) out of 29 gauges with daily NSC>0 with mean of 0.23

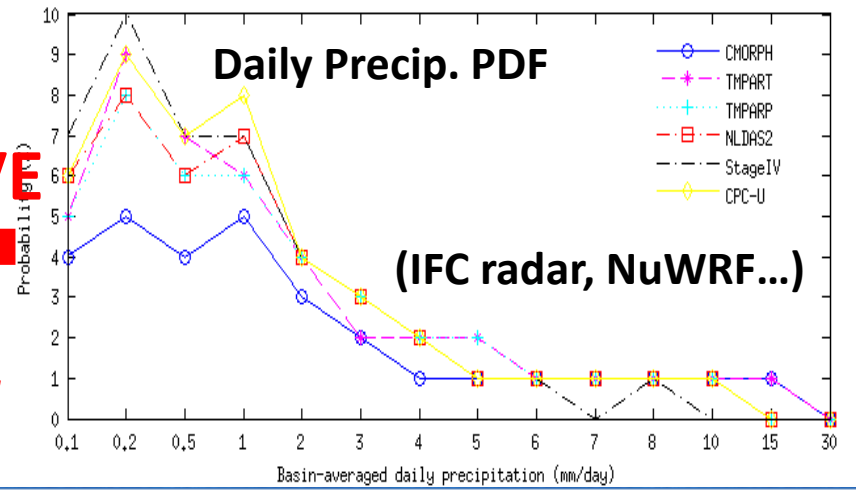
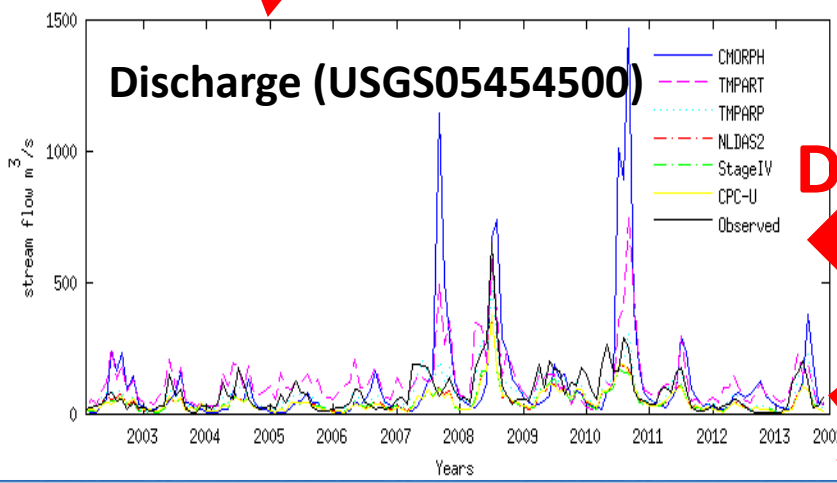
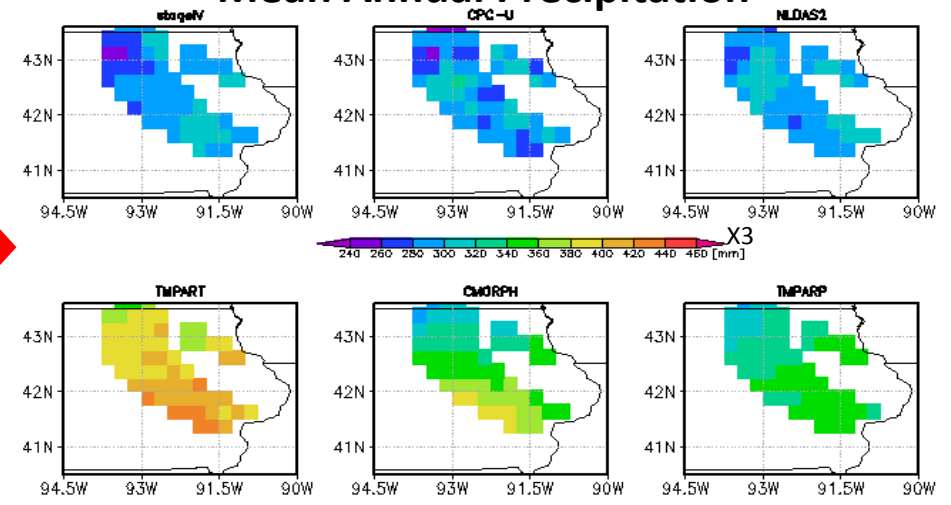


Internet source: April 19, 2013, Des Plaines, IL

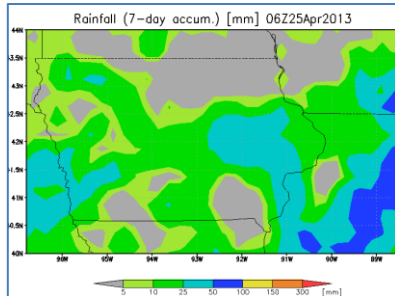




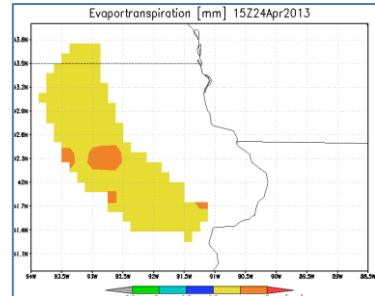
Mean Annual Precipitation



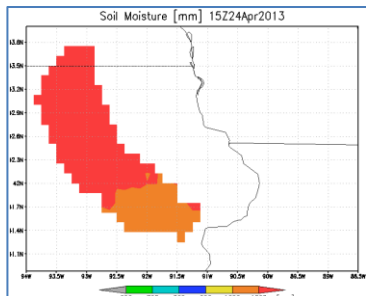
Precipitation



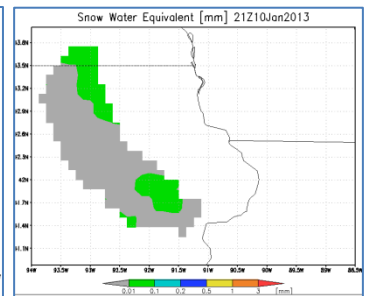
Evapotranspiration



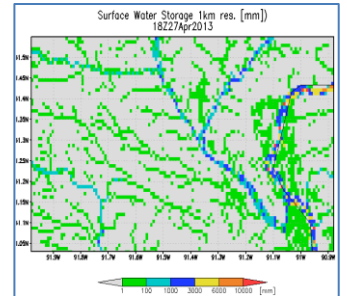
Soil moisture



SWE



SS/Inundation



Summary and Future

1. A new version of the Global Flood Monitoring System (GFMS) has been implemented for real-time application using the U. of Washington VIC community Land Surface Model and a new physically based DRTR routing model from the U. of Maryland for more accurate flood calculation and greater flexibility, including 1 km routing. The VIC/DRTR combination is called the Dominant river Routing Integrated with VIC Environment (DRIVE) system.
2. The evaluation of the DRIVE model shows promising performance in retrospective runs vs. observed streamflow records and in flood event detection against global flood event statistics. Results show impact of dams (higher FAR), potential improvement with improved accuracy of satellite precipitation and greater skill with longer floods.
3. High resolution (1 km) routing and water storage calculations will lead to high resolution inundation mapping for comparison with high resolution visible and SAR imagery of floods.
4. For the future we will also:
 - ▣ be implementing a “dam module” to try to include the impact of man-made structures on the calculations
 - ▣ be evaluating the use of alternative satellite precipitation products and forecast precipitation info. from numerical models (adjusted by the satellite estimates).

Thanks!

